

Resource Constrained 3D Vision Applications



AR/VR Headsets Limited Power



Autonomous Drones Limited Bandwidth



Conventional vs. Equi-Depth Single-Photon Cameras



EDH SPCs maintain distance accuracy with far fewer bins, ideal for resource-constrained applications

3D Sensing with Single-Photon Cameras for Resource-Constrained Applications Kaustubh Sadekar, David Maier, Atul Ingle

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Space Robots Limited Memory

Count-Free Median Tracking Algorithm



Optimized stepping algorithm achieves faster convergence, lower variance and better accuracy than fixed stepping



provides faster convergence than prior methods

(*Ingle & Maier, ICCP 2023)

CV update trajectories for



(RMSE cm \downarrow / 2% inliers \uparrow / 20% inliers \uparrow)

3D Vision Tasks Enabled by EDH SPCs





Hardware Results: Varying Illumination 16-bin HEDH 16-bin PEDH [Ours] 16-bin EWH



12.56 / 11.33 / 69.82



12.55 / 11.33 / 69.82





40.23 / 33.46 / 87.59



10.21 / 96.16 / 97.01



Segmentation

RGB Image | IoU 个|Mean个

32-bin EWH 42.7 | 52.2

32-bin EDH [Ours] 47.8 | 58.3

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